Wind Turbine Blade Composites Assessment Using Non-Contact Ultrasound Method

Rozina Steigmann, Nicoleta Iftimie, Adriana Savin, and Roman Sturm

Abstract—Wind turbine blades (WTB) are one of the most damageable components of a wind turbine system and due to their importance must be tested during the fabrication and before installing. WTB are produced from composite materials with polymeric matrices, most of the stages of producing are manufacturing and can result in different types of defects. Therefore, non-destructive testing (NDT) techniques that provide surface and internal information of the blade are required. In this paper, ultrasonic testing using noncontact transducers for the control of composite type Glass Fiber Reinforced Plastics (GFRP) with orthophthalic polyester resins matrix is presented in order to prove its capabilities for such applications. The mechanical properties determined by above mentioned method are confirmed by destructive tests using Dynamic Mechanical Analysis.

Index Terms—Wind turbine blade, GFRP, nondestructive testing, non-contact ultrasonic method.

I. INTRODUCTION

Historically, wind machines were used for grinding grains in Persia as early as 200BC. Wind turbines have been in use since 1941 when the world’s first megawatt –size wind turbine was connected to the local electrical distribution system in Vermont USA.

Promoting clean energy technologies, environmental protection measures and reduction of greenhouse gas has become a priority in the energy industry. The production of green energy has considerable increased in the last decade. While overall primary energy supply from renewables has grown with 30% from 2004 to 2013, by 2014, renewables supplied approximately 19% of the world’s final energy consumption [1]. Production of wind power saw a similar increase moving from a total installed capacity of 48 GW in 2004 to 318 GW in 2014. The scenario for 2020 foresees a figure of 230 GW (of which 40 GW offshore) producing 581 TWh of electricity, meeting 15.7% of electricity consumption. EU electricity consumption for 2020 was projected to be 3,689.5 TWh [2].

These needs lead to an efficiency in construction and maintenance of wind turbine. While wind turbines on duty are relied to work 90% of the time, many structural flows are still encountered, particularly with the blades. Wind turbine blades (WTB) are one of the most frequently damaged components, can develop cracks at the edges, near the hub or at the tips.

The challenge for the producers is to find materials with operational parameters and conditions leading to the following requirements [3]: focused on stiffness, density, and long-time fatigue; high material stiffness is needed to maintain optimal aerodynamic performance; low density is needed to reduce gravity forces; long-fatigue life is needed to reduce material degradation. Therefore, most of the wind turbine producers combine the use of glass fiber reinforced plastics (GFRP) [4], [5] and carbon fiber reinforced plastics (CFRP) [6], [7] as composites in WTB fabrication (Fig. 1).

But composites exhibit few damage mechanisms: fiber failure, fiber/matrix debonding, matrix cracking, delaminations, dry zones and voids, porosities due to poor curing [9].

Thus, these materials must be inspected, as nondestructively as is possible in order to avoid compromising their quality. Ultrasonic, shearography, thermography and X-ray CT techniques are usually used for the inspection of wind turbine blades [10]-[14]. One of the most suitable methods for nondestructive evaluation of GFRP is ultrasound [15]. While ultrasound and its applications have grown phenomenally in the recent years, the mode by which it is transmitted in a given test medium is severely limited by physical contact between the transducer and the test medium by a liquid gel.

In this paper, it presented a method for nondestructive evaluation of the composite materials used in manufacturing of WTB, involving air-coupled ultrasound transducers. The method presents the advantages of not using contact fluid and not requiring access from the both sides of the samples.
II. STUDIED SAMPLES AND EXPERIMENTAL SET-UP

Typically, for wind turbines blades skins are the composites GFRP. GFRP plates can be reinforced with a variable number of layers. We have studied GFRP having as reinforcement 6 sheets of ravings with 250± 50gm$^2$ density of glass fibers and matrix from different types of unsaturated orthophthalic polyester resins (Fig. 2(a)). The GFRP samples taken into study, made by Helios, Slovenia, have the matrix made by COLPOLY Slovenia. From raw specimens, specimens were cropped in order to make mechanical tests (Fig. 2(b)-(c)).

![Fig. 2. Studied samples: a) raw specimens; b) GFRP studied samples; c) dog-bone shapes from resin.](image)

The features of the samples are presented in Table I.

<table>
<thead>
<tr>
<th>No.</th>
<th>Sample name</th>
<th>Matrix</th>
<th>No. of layers</th>
<th>Fiber value ratio</th>
<th>Density [kg m$^{-3}$]</th>
<th>Observation</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>7201-6l</td>
<td>Colpoly 7201</td>
<td>6</td>
<td>0.6±0.05</td>
<td>1550±20</td>
<td>Medium reactivity resin</td>
</tr>
<tr>
<td>2</td>
<td>7243-6l</td>
<td>Colpoly 7243</td>
<td>6</td>
<td>0.6±0.05</td>
<td>1410±20</td>
<td>Preaccelerated thixotropic</td>
</tr>
</tbody>
</table>

The dog bone samples have the dimensions specified in Fig. 3. The static tests were carried out both for GFRP and the resin matrix using Instron E 8801, having hydraulic fixture for composites (Fig. 4). Samples having dimensions of 50×10×3.9mm$^3$ were cropped for dynamic tests in order to determine complex elastic modulus, shear modulus using a Dynamic Mechanical Analyzer DMA 242 Netzsch Germany with 3 points bending fixture (Fig. 5).

![Fig. 3. Shape and dimensions of dog bone specimens for fatigue tests.](image)

The mechanical characteristics, glass transition temperature and activation energy [16] determined using DMA 242 C and Instron E 8801 are presented Table II.

<table>
<thead>
<tr>
<th>Composite</th>
<th>$E_x/E_y$ [GPa]</th>
<th>$E_z$ [GPa]</th>
<th>$\nu_{xy}$</th>
<th>$T_g$ [°C]</th>
<th>Activation energy [kJ/mol]</th>
</tr>
</thead>
<tbody>
<tr>
<td>7201</td>
<td>9.1</td>
<td>8.2</td>
<td>0.2</td>
<td>82.9</td>
<td>149.6</td>
</tr>
<tr>
<td>7243</td>
<td>8.4</td>
<td>8.2</td>
<td>0.2</td>
<td>105.7</td>
<td>296.4</td>
</tr>
</tbody>
</table>

$E_z$, $\nu_{xz}$ and $G_{xz}$ were determined from the measurement of propagation speed of the ultrasound along the direction Z (according to Fig. 6), the other mechanical properties being determined from the propagation speed of the Lamb waves, the fundamental modes $S_0$ and $A_0$, where $E_z$ is Young modulus, $G_{xz}$ is shear modulus and $\nu_{xz}$ Poisson ratio can be determined by measuring the velocity of longitudinal waves and transversal waves that propagate along z direction [17].

In Fig. 7, it can be observed the variation of Young modulus for each type of composites. Five specimens were cropped from each studied samples. For further investigation with noncontact ultrasound, the first composite (sample 7201) was chosen, having higher Young modulus and density.
In Fig. 8, it presented the results obtained from DMA for 7201-6l sample. The evaluation of elastic properties of GFRP composites was nondestructively made using an ultrasound method with air coupled transducers type NGC 100D25 Ultran Group USA, having the central frequency of 100kHz.

The excitation with rectangular impulses of the emission transducer was made by a Pulser-Receiver PR 5073, Panametrics USA. The received signal is pre-amplified with a preamplifier Ultrasonic Preamp - Panametrics USA and convenient processed in pulser-receiver. The digitization of the signals is made with a digital oscilloscope Wave Runner 64Xi – LeCroy USA coupled with a PC. In order to obtain the changes of the modes in the central incidence point, the emission and reception transducers were mounted so that they formed 11° angles with the normal at composite surface, in composite being generated both longitudinal and transversal ultrasound wave which form together the Lamb waves. The initial distance between the central incidence point and the reception point has been varied between 80mm and 180mm, in 5mm steps, the received wave shape being saved for each situation.

Fig. 7. Young modulus for studied samples.

The signal is presented in time-domain (Fig. 11(a)), frequency domain (Fig. 11(b)) and as spectrogram (Fig. 11(c)).

Fig. 8. DMA results for 7201-6l sample.

Fig. 9. Experimental set-up: a) scheme; b) transducers layout.

Fig. 10. The Lamb waves modes received to different distances between the incidence point and reception point for the studied sample.

III. RESULTS

The collection of signals received for different distances between the central incidence point and the reception one was organized into a bi-dimensional matrix, a linear vector corresponding to each signal. In Fig. 10, it presented several signal registered for the studied sample, the distance where the signal has been received being marked on graph. In Fig. 11(a) is presented the signal received by the reception transducer at the examination of 7201 composite, where the modes A0, S0 and SH0 can be distinguished. For a more reliable identification, the amplitude spectrum has been traced and presented in Fig. 11(b). In Fig. 11(c), it presented the corresponding spectrogram.
of material shape and size. However, it can be used in WTB investigation due to large plane surface of the blade.

ACKNOWLEDGMENT

The manuscript was written through contributions of all authors. All authors have given approval to the final version of the manuscript. All authors contributed equally.

This paper is partially supported by the Romanian Ministry of Education MEN — UEFISCDI, project no. PN-II-PCCA-2013-4-0656 Partnership, project no. PN-II-ID-PCE-2012-4-0437 Ideas, Nucleus program, Contract no. 09-43-01-04 and by the strategic grant POSDRU/159/1.5/S/137750, co-financed by the ESF within the Sectorial Operational Program Human Resources Development 2007–2013.

REFERENCES


Rozina Steigmann has received the master degree in 1999. He has been a Ph.D. Student in 2012, at the Faculty of Physics, University Alexandru Ioan Cuza, Iasi, Romania. Now he is also with the Nondestructive Testing Department, National Institute of Research and Development for Technical Physics, Iasi, Romania.