Capacitor Placement and Sizing in Distorted Distribution Systems Using Simplified Direct Search Algorithm

Fitriana Suhartati, Dimas Fajar U. P., Ontoseno Penangsang, and Adi Soeprijanto

Abstract-In distribution systems, shunt capacitors are added in order to reduce the total active power loss and improve the power factor. However, the installation of shunt capacitors in distorted distribution systems will amplify the harmonics distortion level, if it is not placed in a proper location with harmonics consideration. Therefore, to take into account the presence of harmonic distortion, this paper proposes a simplified direct search algorithm to determine capacitors placement and sizing in distorted distribution systems. This algorithm is connected to harmonic power flow to search the proper location and size of shunt capacitors, which can decrease the total active power loss and increase the power factor, while the total harmonic distortion does not exceed the maximum allowable harmonic distortion level at each bus. To validate the method proposed, this algorithm is tested on 13-bus radial distribution system and 34-bus radial distribution system with harmonic current injection in order of 5, 7, 11, 13, and 17.

Index Terms—Shunt capacitors, active power loss, harmonic power flow, simplified direct search algorithm.

I. INTRODUCTION

In distribution systems, shunt capacitors are installed to compensate reactive power, reduce active power loss, adjust power factor, and improve voltage profile [1]. However, in radial distribution systems, the presence of harmonic distortion have to be considered for compensating reactive power by adding shunt capacitors. Because the installation of shunt capacitors in the distorted distribution systems can cause resonances, increase active power loss, extensive reactive power demand, and overvoltage, if determining the location and size of capacitors without considering the presence of harmonics in the systems [2].

Many research have taken into account the presence of harmonic current and voltage to optimize the placement and size of shunt capacitors using different methods, such as Genetic Algorithm(GA) [1], Genetic Algorithm with Fuzzy Logic (GA-FL) [2] and Fuzzy Set Theory (FST) [3] in a balanced three-phase systems. Moreover, in unbalanced three-phase system, Particle Swarm Optimization (PSO) [4] and Harmony Search Approach (HSA) [5] have been applied to find the optimal location and size of shunt capacitors in the distorted distribution systems.

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Dimas Fajar U. P., Ontoseno Penangsang, and Adi Soeprijanto are with the Power Systems Simulation Laboratory, Department of Electrical Engineering, Sepuluh Nopember Institute of Technology (ITS), Surabaya 60111 Indonesia. (e-mail: dimasfup@gmail.com). This paper proposes a simplified direct search algorithm to determine the efficient location and size of capacitors [6] in distorted radial distribution systems, in order to minimize active power loss, improve power factor, and suppress the harmonic distortion level. The previous paper [6] applied a direct search algorithm for capacitive compensation in radial distribution systems, but the system does not contain any harmonics. In this paper, to consider harmonic distortion, a harmonic power flow algorithm based on backward-forward sweep technique [7] is implemented simultaneously with radial distribution power flow for the fundamental component [8].

II. PROBLEM FORMULATION

A. Objective Function

The objective function(1) is minimized to determine the efficient location and size of capacitors [9]:

$$P_{l} = P_{l}^{(1)} + \sum_{h=h_{0}}^{h_{max}} P_{l}^{(h)}$$
(1)

where

 P_l : total active power loss (kW);

 $P_l^{(1)}$: fundamental component of total active power loss (kW);

 $P_l^{(h)}$: harmonic component of total active power loss (kW); h : the harmonic order;

- h_0 : the smallest harmonic order;
- h_{max} : the highest harmonic order;

B. Constraints

In order to find the best location and size of shunt capacitors which not amplify the harmonic distortion, it is need to limit the power factor, The Total Harmonic Distortion (THD), and the number of compensators by the following constraints:

- 1) The power factor of each bus is not allowed less than 0.8.
- 2) THD of each bus is kept less or equal to 5% as recommended by the IEEE standard 519-1992 [7].

The THD of the *i*th bus is defined by [7]:

$$THD_{i}(\%) = \frac{\sqrt{\sum_{h=h_{0}}^{h_{max}} |V_{i}^{(h)}|^{2}}}{|V_{i}^{(1)}|^{2}}$$
(2)

where *THD_i*: the total harmonic distortion of the *i*th bus(%);

 $|V_i^{(1)}|$: the magnitude of bus voltage at the fundamental frequency;

 $|V_i^{(h)}|$: the magnitude of bus voltage at the harmonic frequency;

 h_0, h_{max} : the minimum and the maximum harmonic

orders;

3) The reactive power injected by shunt capacitors should not exceed the total reactive power demand in the systems [4].

$$\sum Qc < \sum Q \tag{3}$$

where $\sum Q_c$: total reactive power injection;

 $\sum Q$:total reactive power demand before injection;

The reactive power injection based on the standard capacitor sizes available in the literature (in kVAr) are: 150, 300, 450, 600, 750, 900, etc [6].

III. HARMONIC POWER FLOW

Fig. 1 shows a single line diagram of a distorted *n*-bus radial distribution system.



Fig. 1. A single line diagram of a distorted *n*-bus radial distribution system [7]

The harmonic current absorbed by the *i*th bus shunt capacitor is expressed as [7]:

$$[Is^{(h)}] = [Is_i^{(h)}]$$
(4)

The h^{th} harmonic current through the branches are given by:

$$\left[I^{(h)}\right] = \left[\frac{Ih^{(h)}}{Is^{(h)}}\right] \tag{5}$$

The harmonic current through the branches is computed using the backward sweep approach expressed as follows (6):

$$\begin{bmatrix} B_{12}^{(h)} \\ \vdots \\ B_{i-2,i-1}^{(h)} \\ B_{i-1,i}^{(h)} \\ \vdots \\ B_{n-1,n}^{(h)} \end{bmatrix} = \begin{bmatrix} 1 & \dots & 1 & 1 & 1 & \dots & 1 & 1 \\ \vdots & \dots & \dots & \dots & \dots & \dots & \dots & \vdots \\ 0 & \dots & 0 & 1 & 1 & \dots & 1 & 1 \\ 0 & \dots & 0 & 0 & 1 & \dots & 1 & 0 \\ \vdots & \dots & \dots & \dots & \dots & \dots & \dots & \vdots \\ 0 & \dots & 0 & 0 & 0 & \dots & 1 & 0 \end{bmatrix} \begin{bmatrix} Ih_2^{(n)} \\ \vdots \\ Ih_{i-1}^{(h)} \\ Ih_{i+1}^{(h)} \\ \vdots \\ Ih_{n}^{(h)} \\ Ih_{n+1}^{(h)} \\ \vdots \\ Ih_{n}^{(h)} \\ Ih_{n}^{(h)} \\ Ih_{n}^{(h)} \\ Ih_{n}^{(h)} \\ Ih_{n}^{(h)} \\ Ih_{n}^{(h)} \end{bmatrix}$$
(6)

The h^{th} harmonic branch current of any branch can be obtained by

$$\left[B_{ij}^{(h)}\right] = \left[A_{ij}^{(h)}\right]^{T} \left[I^{(h)}\right]$$
(7)

The coefficient vector of branch ij is defined by:

$$\left[A_{ij}^{(h)}\right] = \left[\frac{Ah_{ij}^{(h)}}{As_{ij}^{(h)}}\right] \tag{8}$$

where $\begin{bmatrix} A_{ii}^{(h)} \end{bmatrix}$: the coefficient vector of branch *ij*;

 $\left[Ah_{ij}^{(h)}
ight]$: the coefficient vector of branch *ij* due to the

harmonic current flows of the nonlinear and linear loads through branch *ij*;

 $\left[As_{ij}^{(h)}\right]$: the coefficient vector of branch *ij* due to the harmonic current absorbed by the shunt capacitors;

The coefficient vector consists of 0 and 1 only, for example if a bus harmonic current flows through the branch, then the corresponding position in the coefficient vector will be 1.

The forward voltage sweep is utilized to obtain the harmonic bus voltage with respect to harmonic bus current injections as follows:

$$[V^{(h)}] = [HA^{(h)}][I^{(h)}]$$
(9)

where $\left[V^{(h)}\right]$: the harmonic bus voltages vector;

 $[HA^{(h)}]$: the relationship matrix between the harmonic bus voltages and system harmonic currents;

The harmonic bus voltages of the shunt capacitors are determined by:

$$[V_s^{(h)}] = [HA_s^{(h)}][I^{(h)}]$$
(10)

 $[HA_s^{(h)}]$: the row vectors of the matrix $[HA^{(h)}]$ associated with the buses at which shunt capacitors are installed, and the dimension is Ixn;

Therefore, $\left\lceil HA_{e}^{(h)} \right\rceil$ can be written as:

$$[HA_{s}^{(h)}] = [HA_{sh}^{(h)} : HA_{ss}^{(h)}]$$
(11)

 $[HA_{sh}^{(h)}]$: the elements of (n-1) columns in vector $[HA_s^{(h)}]$ are associated with the harmonic currents of the nonlinear and linear loads;

 $[HA_{ss}^{(h)}]$: the last element in $[HA_s^{(h)}]$ is related to the harmonic currents of the shunt capacitor at bus *i*;

The harmonic voltage on the *i*th bus shunt capacitor is expressed in terms of the harmonic impedance of the shunt capacitor defined as:

$$Vs_i^{(h)} = -Is_i^{(h)} xZs_i^{(h)}$$
(12)

where

where

 $Is_i^{(h)}$: the harmonic current of the shunt capacitor on the *i*th bus;

 $Zs_i^{(h)}$: the harmonic impedance of the shunt capacitor on the *i*th bus:

The harmonic bus voltages are iteratively computed until a predefined threshold is reached.

$$\left|V_{i}^{(h),k+1} - V_{i}^{(h),k}\right| \le \varepsilon \tag{13}$$

where

 $V_i^{(h),k+1}$: the harmonic voltage of the *i*th bus at the (k+1)th iteration;

 $V_i^{(h),k}$: the harmonic voltage of the *i*th bus at the *k*th iteration;

k : the iteration;

 ε : the threshold;

The total active power loss for the h^{th} harmonic order is:

$$P_l^{(h)} = \left[R^{(h)} \right]^T \cdot \left| \left[A^{(h)} \right] \cdot \left[I^{(h)} \right] \right|^2 \tag{14}$$

where $[R^{(h)}]$: the total branch resistance for the h^{th} harmonic order.

IV. SIMPLIFIED DIRECT SEARCH ALGORITHM

According to the radial power flow analysis for the fundamental and harmonic components, the simplified direct search algorithm is implemented to find the efficient location and the size of the shunt capacitors. Based on the objective function(1), the algorithm can be described in these following steps:

- 1) The uncompensated loss in the system is considered maximum total active power loss.
- Set the reactive power of all buses to zero or nearest zero by adding shunt capacitor (in kVAr). This is considered as minimizing the total active power loss.
- 3) Try to find the location and size of capacitors in such away the total active power loss is measured and its value is between the maximum and minimum, however only the compensation which satisfy the constraints are listed.
- 4) The size of capacitors in the bus with the highest loss reduction will be reduced by multiple of the smallest capacitor size available.
- 5) Then, find the minimum total active power loss.

Fig. 2 below shows flowchart of the algorithm explained above.



Fig. 2. Flowchart of simplified direct search algorithm.

V. SIMULATION RESULTS

To validate the proposed method, the algorithm is applied to 13-bus test system and 34-bus test system as shown in Fig. 3 and Fig. 4 below.



Fig. 3. Single line diagram of 13-bus test system.



Fig. 4. Single line diagram of 34-bus test system.

A. Test I: 13-Bus System

In 13-bus test system, a harmonic current source was injected into bus 2 and 9. The harmonic injection current was in order of 5, 7, 11, 13, and 17. The load data of 13-bus system is listed in Table II (Appendix I).

In the uncompensated system, the measured total reactive power load in the 13-bus system was 4430 kVAr and the total active power loss was 42.796 kW. Using harmonic power flow analysis, the computed minimum $\cos \theta$ in the system was 0.15 and the maximum THD was 6.036%.

Using the simplified direct search algorithm, the compensated system was constructed. The total reactive power injection in the system was 3750 kVAr and the total active power loss reduced to 7.347 kW. The minimum $\cos \theta$ in the system became 0.8, whereas the maximum THD was 4.684%, lower than uncompensated power loss.

B. Test II: 34-Bus System

Table III (Appendix I) shows the load data of 34-bus. In this bus test system, a harmonic current source was injected into bus 5, 11, 15, 25 and 33, with the harmonic injection current was in order of 5, 7, 11, 13, and 17.

In the uncompensated system, the measured total reactive power load in the 34-bus system was 4636.5 kVAr and the total active power loss was 323.24 kW. Using harmonic power flow analysis, the computed minimum $cos \theta$ in the system was 0.771 and the maximum THD was 6.317%.

After compensators were added into the system, the measured total reactive power injection in the system was 3150 kVAr, while the total active power loss became 205.9 kW. The minimum $\cos \theta$ in the system was increased to 0.842, whereas the maximum THD was reduced to 4.8%.

C. Comparison with Particle Swarm Optimization (PSO) Method

TABLE I: THE COMPARISON OF REACTIVE COMPENSATION									
13-Bus Systems									
	without	compensation							
	compensation	by simplified	by PSO						
		direct search							
Q total (kVAR)	4430	3750	3600						
Ploss total (kW)	42.796	7.347	7.829						
$\cos \theta$ average	0.535	0.938	0.907						
THD average (%)	4.675	3.993	3.995						
34-Bus Systems									
Q total (kVAR)	3633.5	3150	2400						
Ploss total (kW)	323.24	205.9	209.004						
$\cos \theta$ average.	0.829	0.968	0.938						
THD average (%)	4.119	3.173	3.255						

Table I shows the comparison between simplified direct search algorithm and particle swarm optimization (PSO) method to determine the efficient placement and size of shunt capacitors.

Using the proposed algorithm, the total power loss can be reduced in average of 35.449 kW for 13-bus system and 117.34 kW for 34-bus system. It also increased the average power factor up to 0.403 in 13-bus system and 0.139 in 34-bus system. The decreasing of THD average until 0.682% for 13-bus system and 0.946% for 34-bus system can also be achieved. While compensation method using PSO reduced the average of total power loss to 34.967 kW for 13-bus system and 114.236 kW for 34-bus system. Increased the average power factor up to 0.372 in 13-bus system and 0.109 in 34-bus system and also decreased the THD average until 0.680% for 13-bus system and 0.864% for 34-bus system. However the total reactive power injection by the proposed method in 13-bus system was 150 kVAr (greater than PSO), and 750 kVAr (greater than PSO) in 34-bus system.

VI. CONCLUSION

A simplified direct search algorithm for designing compensation in distorted distribution systems resulted the total active power loss reduction, power factor correction, and decreasing of total harmonic distortion level. These results were obtained from simulation for 13-bus and 34-bus systems. The simulation results have verified that the reactive compensation by simplified direct search algorithm yield slightly more reduction on the total active power loss and the THD compared to PSO, however the total reactive compensation by the proposed method was greater than PSO. A challenging research of the application of the proposed approach for unbalanced radial distribution systems is considered for future work.

APPENDIX I

TABLE II: LOAD DATA OF 13-BUS SYSTEMS								
Line	From	То	R (Ω)	$X(\Omega)$	P(kW)	Q(kVAR)		
no.	bus	bus						
1	1	2	0.117	0.048	100	30		
2	2	3	0.107	0.044	20	730		
3	3	4	0.165	0.046	150	225		
4	2	5	0.150	0.042	50	10		
5	5	6	0.150	0.042	120	540		
6	6	7	0.314	0.054	40	700		
7	5	8	0.210	0.036	75	90		
8	2	9	0.314	0.054	50	150		
9	9	10	0.210	0.036	125	825		
10	5	11	0.131	0.023	210	800		
11	11	12	0.105	0.018	80	300		
12	11	13	0.157	0.027	95	30		

TABLE III: LOAD DATA OF 34-BUS SYSTEMS							
Line	From	To	R (Ω)	$X(\Omega)$	P(kW)	Q(kVAR)	
no. 1	bus 1	2	0.117	0.048	230	190	
2	2	3	0.107	0.044	0	0	
3	3	4	0.165	0.046	230	190	
4	3	13	0.157	0.270	72	45	
5	4	5	0.150	0.042	230	190	
6	5	6	0.150	0.042	0	0	
7	6	7	0.314	0.540	0	0	
8	6	17	0.179	0.050	230	190	
9	7	8	0.210	0.036	230	190	
10	7	28	0.105	0.018	75	48	
11	8	9	0.314	0.540	230	190	
12	9	10	0.210	0.036	0	0	
13	10	11	0.131	0.023	230	190	
14	10	31	0.157	0.027	57	34.5	
15	11	12	0.105	0.018	137	84	
16	13	14	0.210	0.036	72	45	
17	14	15	0.105	0.018	72	45	
18	15	16	0.052	0.009	13.5	7.5	
19	17	18	0.165	0.046	230	190	
20	18	19	0.208	0.047	230	190	
21	19	20	0.189	0.043	230	190	
22	20	21	0.189	0.043	230	190	
23	21	22	0.262	0.045	230	190	
24	22	23	0.262	0.045	230	190	
25	23	24	0.314	0.540	230	190	
26	24	25	0.210	0.036	230	190	
27	25	26	0.131	0.023	230	190	
28	26	27	0.105	0.018	137	85	
29	28	29	0.105	0.018	75	48	
30	29	30	0.157	0.027	75	48	
31	31	32	0.210	0.036	57	34.5	
33	32	33	0.157	0.027	57	34.5	
33	33	34	0.105	0.018	57	34.5	

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